

肌肉骨骼危害防制 與現場改善

陳協慶 國立臺北科技大學 imhcchen@ntut.edu.tw

課程內容



- 肌肉骨骼危害現況與我國法規
- 肌肉骨骼危害與形成之機轉
- 肌肉骨骼危害防制流程
- 肌肉骨骼危害防制改善案例
- 檢核工具之分類、選擇與使用





肌肉骨骼危害現況 與我國法規



相關法規



人因性危害防止計畫係指事業單位為執行 「職業安全衛生法」第六條第二項以及其施 行細則第十條第二項、勞工安全衛生設施規 則第三百二十四條之一條等相關法規之規定 要項,並參酌勞工安全衛生管理規章、勞工 安全衛生管理計畫及台灣勞工安全衛生管理 系統(TOSHMS)內容訂定。



職業安全衛生法第六條第二



雇主對下列事項,應妥為規劃及採取必要之安全衛 生措施:

- 一. 重複性作業等促發肌肉骨骼疾病之預防。
- 二. 輪班、夜間工作、長時間工作等異常工作負荷促發疾 病之預防。
- 三. 執行職務因他人行為遭受身體或精神不法侵害之預防。
- 四. 避難、急救、休息或其他為保護勞工身心健康之事項。
- 1. 違反規定致發生職業病,處新台幣三萬元以上三十萬元以下罰鍰。
- 違反規定,經通知限期改善屆期未改善處新台幣三萬元以上十五萬元以下罰鍰。



職業相關之肌肉骨骼傷害

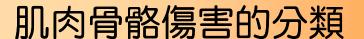


- 由於職業暴露於人因相關危害,因而引發 或加重之肌肉、骨骼、周邊神經或神經血 管系統疾病或傷害。
- 人因相關危害指對於肌肉骨骼系統有可能 造成傷害或疾病的生理壓力來源(physical stressor)或職場因子。





肌肉骨骼危害與 形成之機轉





急性:肌肉:刀傷、撞傷、拉傷

其他組織:(同)

慢性:肌肉

持續收縮→新陳代謝超負荷

(或微傷害)→乳酸積聚→疲勞→酸痛發炎

其他組織(關節面、腱鞘、滑液囊) 摩擦→發炎→碳酸鹽的沈積鈣化→ →

摩擦力急遽升高→病變



常見的肌肉骨骼傷病



• 肩頸: 旋轉肌袖肌腱炎、緊張性頸痛、頸椎疾病

• 手臂/手肘: 肱上髁炎、胸廓出口症候群

 手腕/手部: 腱鞘囊腫、肌腱炎、肌腱滑膜炎(奎 緬氏症、扳機指)

• 下背部: 椎間盤突出症、坐骨神經痛、下背痛

• 下肢: 地毯工人膝、足部疼痛、膝關節炎

• 神經血管: 腕道症候群、雷諾氏症















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	工作	傷害	
	1.研磨	腱鞘炎、胸廓出口症、腕道 症候群、奎緬氏症、旋前肌 併合症	<u>I</u>
	2.沖壓	腕部及肩部肌腱炎、奎緬氏症	重由
	3.頭頂上方組裝	胸廓出口症、肩部肌腱炎	Ą
	4.生產線組裝	腕部及肩部肌腱炎、腕道症 候群、胸廓出口症	手
	5.打字,打孔 收銀員	頸部緊繃、胸廓出口症、腕 道症候群	青指
	6.裁切	胸廓出口症、奎緬氏症、腕 道症候群	重由
١	7.小零件組裝	頸部緊繃、胸廓出口症、腕 部肌腱炎、肱上髁炎	作勝
١	8.信差	肩部問題、胸廓出口症	扂
	9.音樂家	腕部肌腱炎、腕道症候群、 肱上髁炎、胸廓出口症	重打
	13.貨車駕駛	胸廓出口症	打

腕部肌腱炎

e maker

重複性腕部作業,局部拉展,震動,劇烈尺偏,重複的前臂內轉

職業傷害因

重複性劇烈腕部外展/屈曲,重複性局部外展/屈曲,前臂外翻重複性尺偏於推移控制上

手臂持續過度伸直,手部高舉過局部

手臂伸出,外展或屈曲小於60度;重複性腕部 作業

靜態且受限的姿勢;手臂外展/屈曲;快速之手 指作業;手掌中心受壓力;尺偏

重複性局部屈曲,重複性尺偏,重複性腕部屈曲/外展,手掌中心受壓力

伸長受限姿勢,劇烈尺偏及拇指受力;重複性 腕部作業;劇烈腕部外翻及內轉

肩部背負過重負荷

重複性劇烈腕部作業,手掌中心受壓力,肩部 拉伸外展/屈曲,劇烈的腕部外展及前臂內轉 拉伸肩部外展及屈曲

重複性腕部作業



工作相關之傷害及職業傷害成因2/

7. 小零件組裝

8.信差

9.音樂家

10.工作台作業

11. 手術室人員

12. 包裝

13.貨車駕駛

14.Core maker

15.家務,烹飪

16.木匠,泥水匠

17. 倉儲, 運輸

18.物料搬運

伐木/建築

/肉品處理

部肌腱炎、肱上髁炎

局部問題、胸廓出口症

肱上髁炎、胸廓出口症

尺關節嵌制

奎緬氏症

繃、腕道症候群、奎緬氏症 劇烈尺偏

胸廓出口症

腕部肌腱炎

奎緬氏症、腕道症候群

胸廓出口症、肩部肌腱炎

胸廓出口症、肩部肌腱炎

肩部肌腱炎、肱上髁炎

奎緬氏症、腕道症候群

頸部緊繃、胸廓出口症、腕 伸長受限姿勢,劇烈尺偏及拇指

腕部作業;劇烈腕部外翻及內轉

信部背負過重負荷

腕部肌腱炎、腕道症候群、 重複性劇烈腕部作業,手掌中心受壓力,局部

拉伸外展/屈曲,劇烈的腕部外展及前臂內轉

持續手肘屈曲並施壓於尺骨連接處

胸廓出口症、腕道症候群、 拉伸肩部屈曲,重複性腕部屈曲,尺偏(持牽開

腕部及肩部肌腱炎、頸部緊 肩部拉伸負荷,重複性腕部作業,過度使用,

拉伸肩部外展及屈曲

重複性腕部作業

擦拭,清洗,快速腕部旋轉作業

腕道症候群、蓋式隧道症候 錘打,壓力集中於手掌中心

可及範圍高過頭部,局部負重並處於非自然姿

肩部背負負荷

重複丟擲笨重之負荷(物件)

尺偏,費力屈曲手腕



過度使用傷害之病理機轉

- 重複性張力 (repetitive strain)
 - → 發炎、腫脹、疼痛、血流供應減少、神經末梢 過度刺激

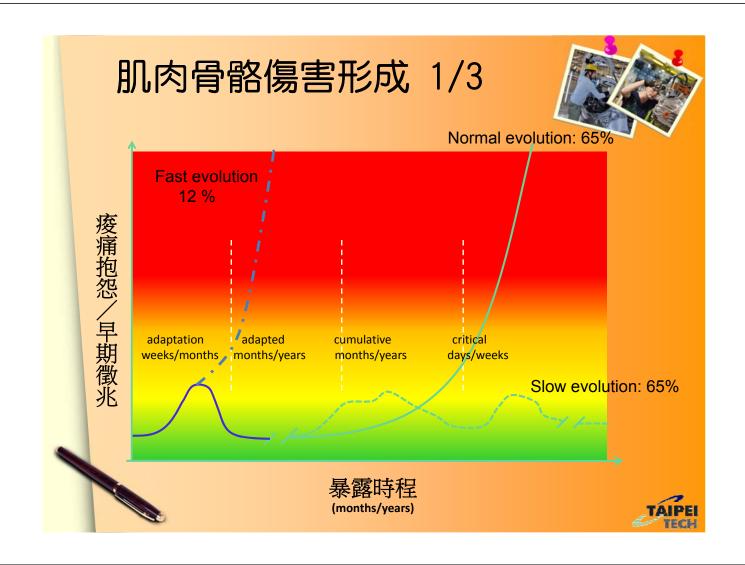


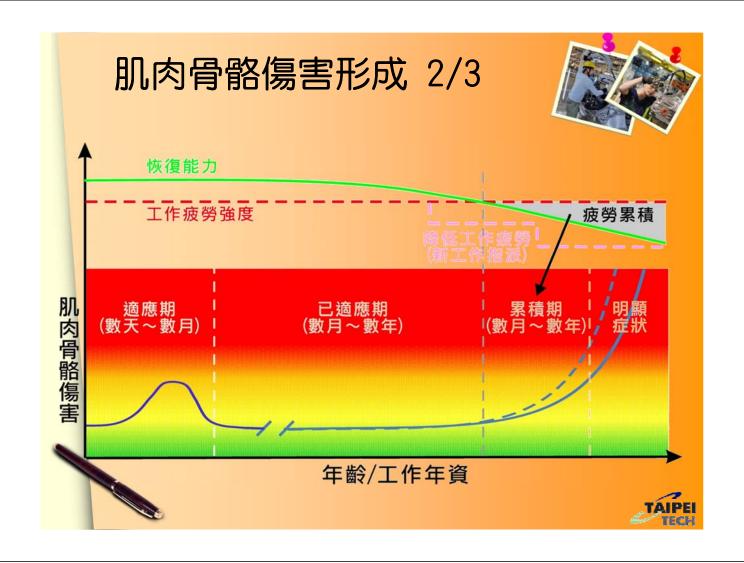


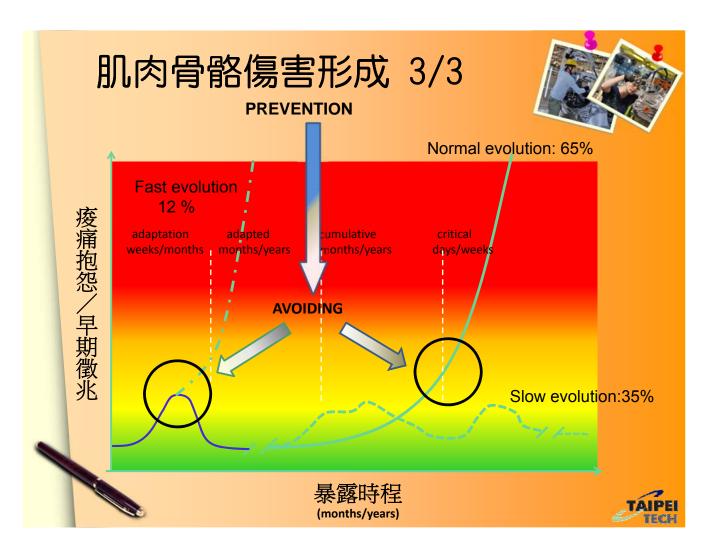


















職業相關危險因子(下背)





危險因子	強烈證據	足夠證據	證據不足
抬舉/用力活動	✓		
不當姿勢		✓	
全身性振動	✓		
重體力活動		✓	
靜態工作姿勢			✓



職業相關危險因子



危險因子	肩頸	肩膀	手肘	手部/ 手腕	肌腱炎
高重複動作	+	+	?	+	+
高施力	+	?	+	+	+
不良姿勢	++	+	?	?	+
振動暴露	?	?		+	
綜合因子			++	++	++

++:強烈證據;+:足夠證據; ? :證據不足



肌肉骨骼危害防制的困難度

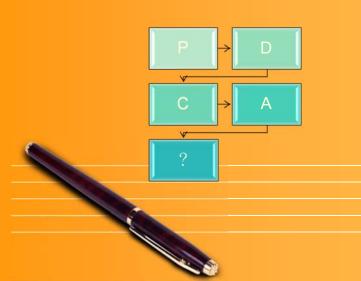


- 肇因於多重危害暴露,造成危害暴露量化 (風險評估)上的困難
- 年齡老化因素與工作內容變化增加評估上的困難度
- 個人與社會心理因素





肌肉骨骼危害防制流程



人因改善三步驟



確認潛在或存在問題 (文獻、傷害、症狀報告) 分析工作中 危險因子的 暴露(檢核 表、工作分 析)

2

評估工作危 害程度(等 級)擬定改 善方案

3

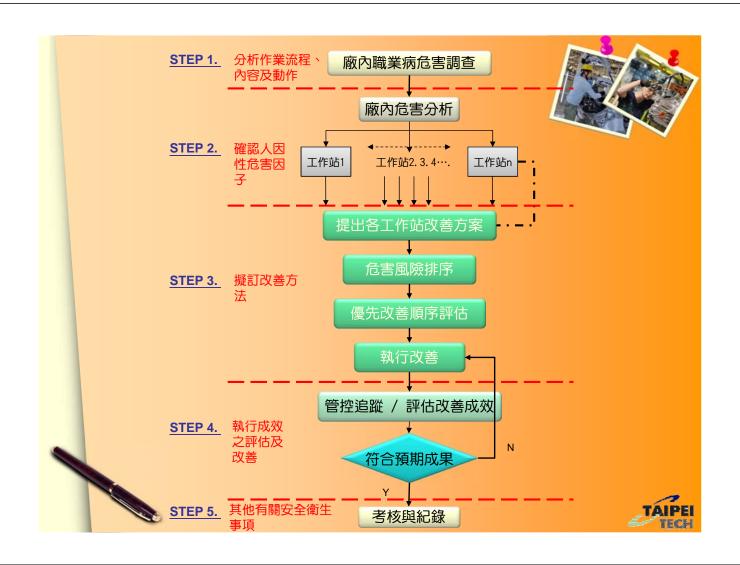


勞工安全衛生設施規則第324-1

雇主使勞工從事重複性之作業,為避免勞工因姿勢不良 過度施力及作業頻率過高等原因,促發肌肉骨骼疾病, 應採取下列危害預防措施,並將執行紀錄留存三年:

- 一. 分析作業流程、內容及動作。(辨識有危害作業)
- 二. 確認人因性危害因子。(確認該作業之危害因子)
- 三. 評估、選定改善方法及執行。(依據危害因子規劃改善)
- 四. 執行成效之評估及改善。(評估危害及傷病是否消除)
- 五. 其他有關安全衛生事項。
- 前項危害預防措施,事業單位勞工人數達一百人以上者,雇主 應依作業特性及風險,參照中央主管機關公告之相關指引,訂 定人因性危害預防計畫,並據以執行;於勞工人數未滿一百人 者,得以執行紀錄或文件代替。

TAIPEI



肌肉骨骼傷害調查

- 1) 現況調查:包含勞保職業病案例、通報職業病案例、就醫紀錄、病假與工時損失紀錄等。
 - > 健康與差勤監測
 - > 探詢員工抱怨
- 2) 主動調查:全體員工的自覺「肌肉骨骼傷害問卷調查表」
- 3)確認改善標的:就上開現況調查的健康與差勤 監測、探詢員工抱怨與主動調查等三項資料, 將個案判定為確診疾病個案、疑似有危害個案、 無危害個案三級



危害狀況判定



危害因子

有危害

無危害

人員反應

無抱怨

有抱怨





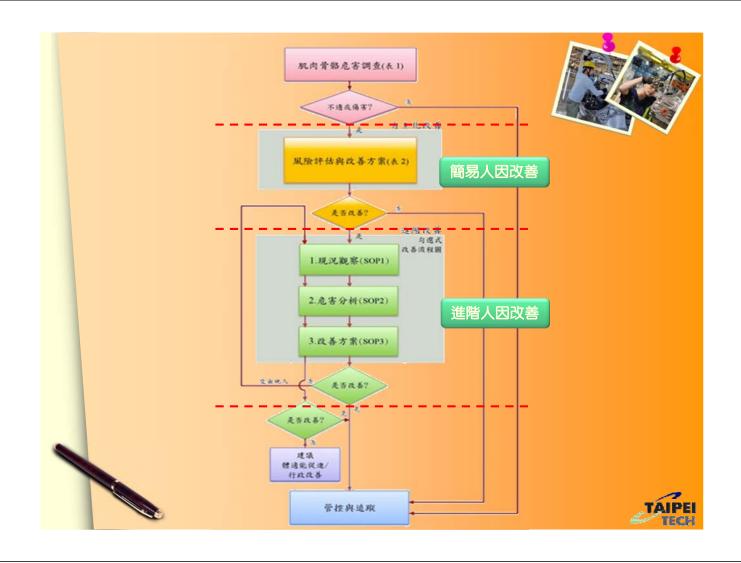


















進階改善方案:SOP表單

- 改善方案: SOP表單(1)
 - •以外力取代-1
 - •改變工作方法
 - •改變工作姿勢







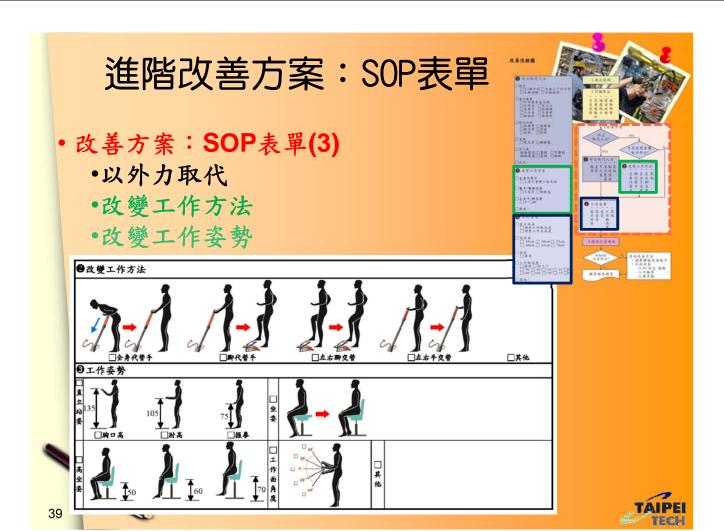
進階改善方案:SOP表單

- 改善方案: SOP表單(2)
 - •以外力取代-2
 - •改變工作方法
 - •改變工作姿勢









人因危害因子控制





工程/人因控制



行政控制

- 工作常規
- 訓練
- 員工派工評估
- 3

個人防護裝置 ← 部分裝置實際效用未明





肌肉骨骼危害防 制改善案例



簡易人因工程改善 1/6



- 工作台









bending







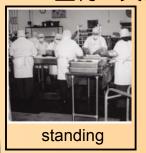






簡易人因工程改善 2/6

- ・工作站部件調整
 - 坐椅、其他設備工具



















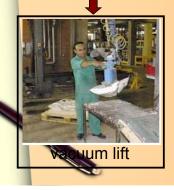
- ・改變作業方式一應用輔具
 - 省力設備















簡易人因工程改善 4/6

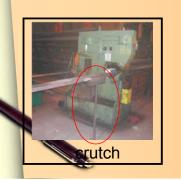


- 支架















簡易人因工程改善 5/6

- ・改變作業方式一應用輔具
 - 機器、輸送設備、手工具





heavy load





long handle



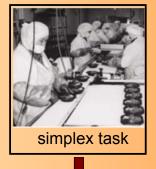




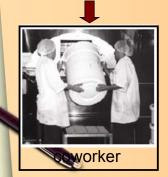
簡易人因工程改善 6/6

- ・改變作業方式一人員
- ・使用護具

















案例一 馬達外殼車削

1/4

- 現況說明
 - 設施佈置
 - · CNC車床 (高度100公分)
 - 工具、工件
 - ・馬達底座(重量25公斤)
 - 木箱深度 (約80公分)
 - 作業員
 - 男性1名,約40歲

→作業描述

- · 彎腰 (0~90°)
- 抬舉、搬運(80~100 cm)
- 12分鐘(5/h, 40/8h)





案例一 馬達外殼車削 2/4

• 問題陳述

- 過度施力
- 高重覆動作
- 低溫
- 震動
- 不良的姿勢









案例一 馬達外殼車削



• 改善方案

- 過度施力:以外力取代?(天車、省力設備、支架)

- 不良的姿勢: 自然、省力的工作姿勢









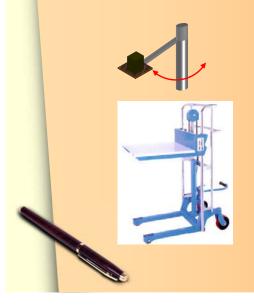


案例一 馬達外殼車削



改善方案: 旋轉臂









案例二 TV模組包裝 1/2



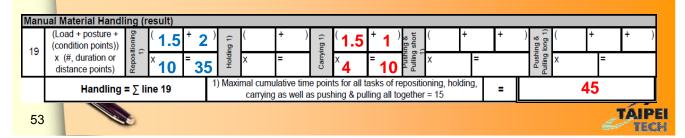


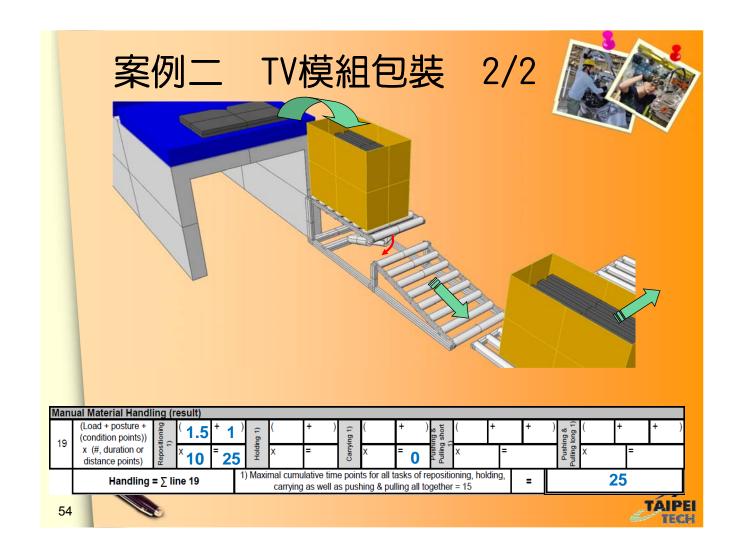
工作狀況:

- ❖ 抬舉TV
- ❖ 攜行 2.5 m
- ❖ 放置裝箱(微彎腰姿勢)
- ❖ 4 TVs /箱

TV重量:10kg

時間:>1000次/班







人因性危害檢核工具 之分類、選擇與使用

陳協慶 教授國立臺北科技大學

Contents



- Choose Appropriate Assessment Tools
- 2 Analysis & Measurement Tools
- 3 EAWS (part1~3)

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Choose Appropriate Assessment Tools



不同系統性觀察法之評估內容

方法	姿勢	負荷/ 施力	動作 頻率	持續 時間	恢復/休 息時間	振動	* 其它
OWAS	1	1					
RULA	1	1	√				
EAWS	1	1	√	√	√	√	√
NIOSH Lifting Eq.	1	4	4	1			1
KIM	1	1	√	V			√
The Strain Index	1	4	4	4			1
OCRA	√	1	√	√	√	√	√
ACGIH TLVs		. 1	1	V			

*These include, mechanical compression, glove use, environmental conditions, equipment, load coupling team work, visual demands, psychosocial and individual factors.

David GC, 2005, Occupational Medicine

Question



·應該先選擇評估工具後再進行(暴露)資料收集,還是先收集現有資料再選擇可用的工具?





Question



• 選擇工具時應考慮以下哪些因素? (ex. 工作姿勢、施力大小、重複次數、受傷部位、工作時程、環境因素、使用工具、工作內容/ 組成、性別、體型、年齡、??)











選擇評估工具之準備



確認存在的危害因子

調查疲勞、傷痛及肌肉骨骼抱怨部位

比對危害因子與傷痛部位之關係

瞭解各評估工具的應用範圍(傷害部位)與其所考量 之危害因子



常見人因危害評估工具分類

a a street			
分類	評估工具	評估部位	分級
上肢	簡易人因工程檢核表	肩、頸、手肘、腕、軀幹、腿	I,篩選
	Strain Index	手及手腕	Ⅱ,分析
	ACGIH HAL-TLV	手	Ⅱ,分析
	OCRA Checklist	上肢,大部分手	Ⅱ,分析
	KIM-MHO (2012)	上肢	Ⅱ,分析
	OCRA Index	上肢,大部分手	Ⅲ,專家
	EAWS (4)	肩、手肘、腕	Ⅲ,專家
背部	簡易人因工程檢核表	肩、頸、手肘、腕、軀幹、腿	I,篩選
	KIM-LHC	背	I,篩選
	KIM-PP	背	I,篩選
	NIOSH Lifting eq.	背	Ⅱ,分析
	EAWS (3)	手臂、軀幹、腿	Ⅲ,專家
全身	RULA, REBA	肩、頸、手肘、腕、軀幹、腿	Ⅲ,專家
	OWAS	背、上臂和前臂	Ⅲ,專家
	EAWS (1-3)	肩、手、軀幹、腿	Ⅲ,專家

註)|級可謂篩選:是簡單的評估工具,不要求工作條件的詳細知識,不涉及姿勢或力的定量評估; 可以由工人自己使用。||級可謂分析:工具需要更長的時間來使用(大約一小時),並需要考慮更 多。因素。|||級可謂專長:工具要複雜許多,需要更長的時間來使用,大多需要錄影分析、測量方 法、與一物力學上的特定技能。

Question



若工作包含有多種的作業模式,需對工作中的不同作業挑選不同的評估工具?或是選擇危害風險最高的作業進行評估?



如以多種工具評估同一作業的危害風險,應採用風險較高的判定結果,以避免低估危害的存在



可整合不同作業條件之工具





評估工具	評估部位	評估作業
NIOSH eq.	背	抬舉
OCRA Index	上肢	上肢重複性動作
EAWS _{1~3}	全身	姿勢、施力、搬運



適用之肌肉骨骼危害風險 評估工具



理想的評估工具(Chris Hamrick, 2006):

- □ 預測能力 → 靈敏度 (sensitivity)
- □ 健適性 → 涵蓋度/可用度(usability)
- □便宜
- □非侵入性
- □快速
- □易於使用



評估工具危害風險判定



Stop working adverse health risks are likely

Maximum —— Permissible Limit

caution is indicated
with respect to
potential risks for
adverse health effects

Action Limit -

adverse health effects have not been clearly documented



上肢重複性作業測試分析(2014)





生產線(果醬瓶)裝箱

- 1kg 瓶 (10 min)
- 250g 果醬瓶 x 2 (10 min)

沖床加工作業

- 900g 工件 (10 min)
- 250g 工件 (10 min)



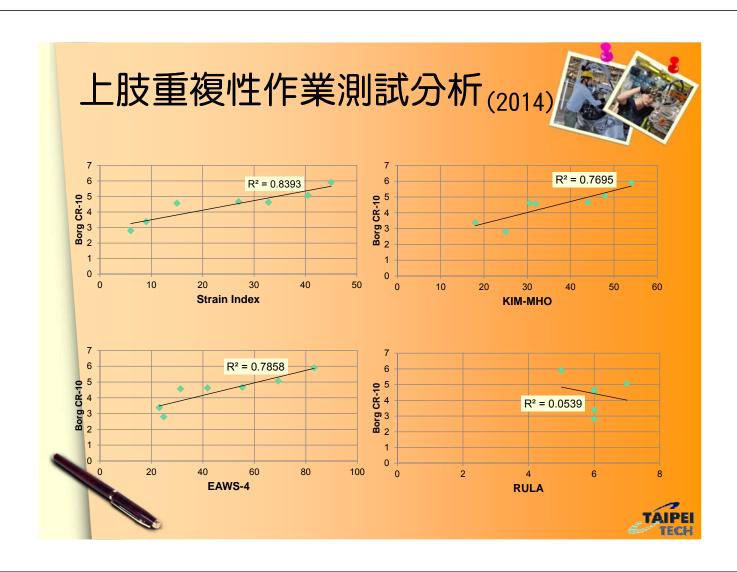






牆面披土(5 min)

牆面刮漆(5 min)



重複性作業肌肉骨骼危害風險評估工具比較

	披土	漆天花板	漆牆	沖床900	裝罐1000	沖床250	裝罐250	
Borg (CR-10)	5.9	5.1	4.7	4.6	4.6	3.4	2.8	Pearson r
SI	45.0	40.5	27.0	32.8	15.0	9.0	6.0	0.92
OCRA	45.2	25.9	16.1	10.5	9.9	5.8	5.4	0.85
HAL	1.75	0.80	1.02	0.68	0.81	0.45	0.56	0.81
EAWS ₄	83.2	69.3	55.4	41.8	31.3	23.1	24.8	0.89
МНО	54.0	48.0	44.0	30.5	32.0	18.0	25.0	0.88
RULA	5	7	6	6	6	6	6	-0.27

高體力負荷界限

疲勞舒適界限



重複性作業肌肉骨骼危害風險 評估工具遴選 管理人員 一、謂分別以"(現場)官理人員」及"(人囚)等外 者的立場,分別對三項原則的重要性給予適當權重(%準確性 0.306 0.506 0.256 適用/涵蓋性 0.313 項權重之總和為100%。 人因專 管理人員 0.438 便利性 0.181 準確性 ■管理人員 ■人因專家 5 涵蓋性 便利性 **EAWS OCRA** RULA HAL-TLV KIM-MHO 評估工具

Summary



評估工具的選擇首重:

- Work nature & musculoskeletal risk factors
- Injuries (back, shoulder / neck, upper limb)
- Work type (continuous, intermittent, ...)
- Exposure (duration, rest / break arrangement, ...)





Analysis & Measurement Tools



Video Analysis

Why doing video analysis

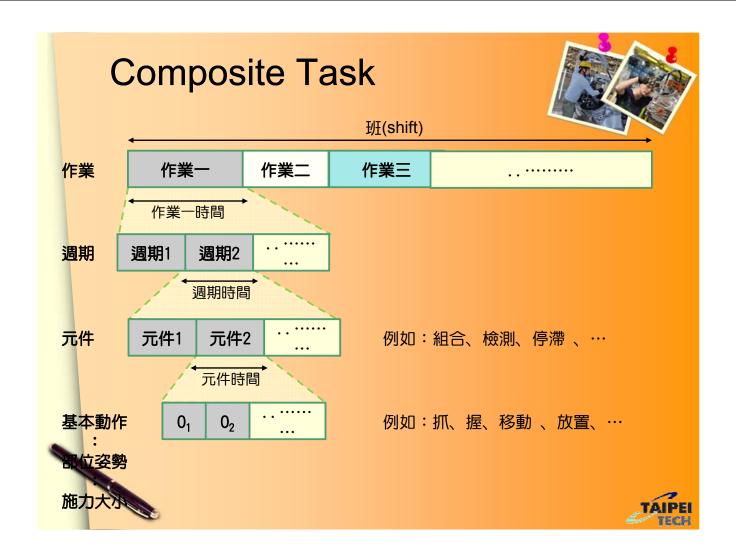


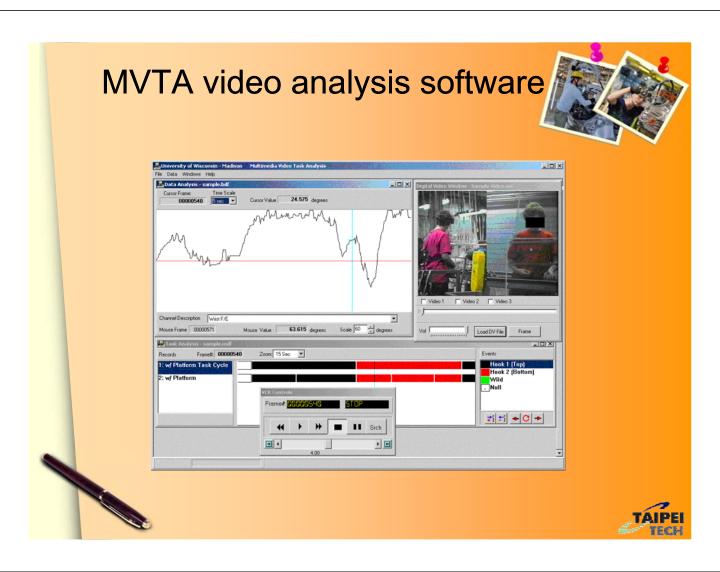
Postures in fast movement can not be registered easily.

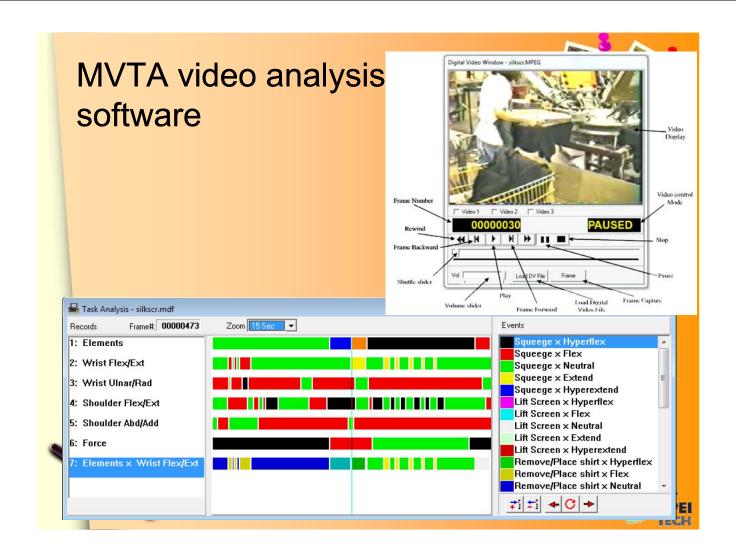
Complex movements requires to be recognized carefully.

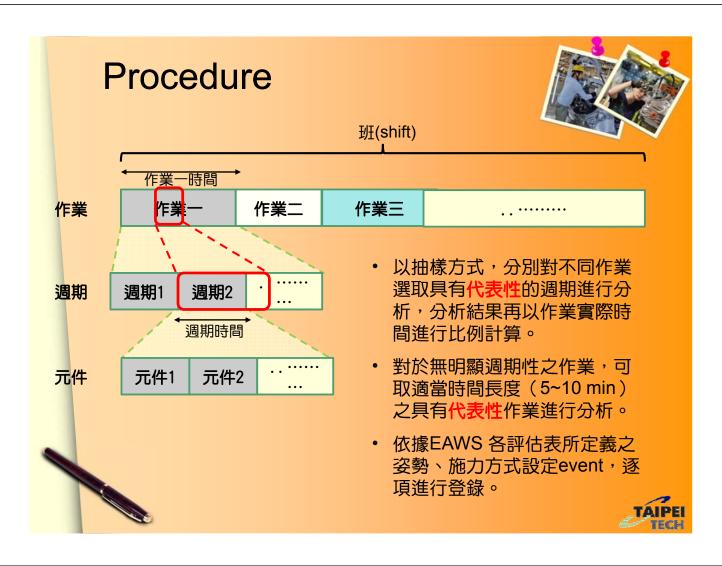
Duration of each event is needed to be recorded and summarized.













Force Measurement

Why measuring force



- · Force can't be seen.
- Too many factors can affect hand/finger force:
 - Weight, resistance, reaction force
 - · Handles: size, shape, materials
 - Gloves
 - √ friction may prevent objects from slipping out of the hand as it opens
 - ✓ stiff or bulky gloves may interfere with closing the fist
 - Mechanical aids: supports, hoists, carts, conveyors, power tools
 - Torque control for threaded fasteners
 - Work pace
 - Quality
 - Maintenance

Psychosocial stress





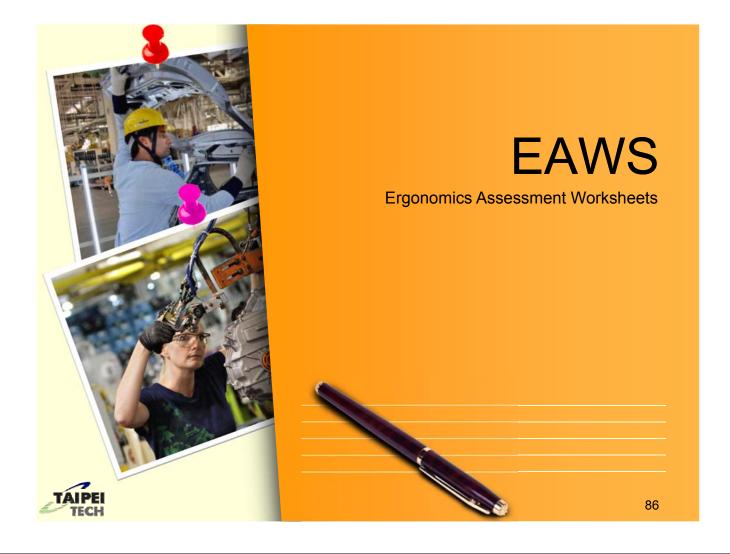


Procedure



- Measure workers' subjective exertions and their maximal exertions, if possible.
- Judge workers' response by your knowledge.
- Validate the magnitude by yourself.





Name of the worksheet



Task: Analyst: Task duration:	Date: UAS-Analysis:
	UAS-Analysis:
Ergonomic Assessment Worksheet V1.3	
Ergonomic Assessment Worksheet V1.3	
Ergonomic Assessment Worksheet V1.	
	5.3
Plant Gender of operator m f Bc	dy height
Line MTM Analysis Ar	alyst
Task / Workplace Task duration [sec] Da	ite

Application notes



- ➤ Works best for short cycled tasks (cycle time ≤ 5 min)
 - For cycle time above 30 minutes the amount of tasks often exceeds the capabilities of the observer and makes a "pen and paper"-analysis of a certain section impractical
 - No peek loads for long periods





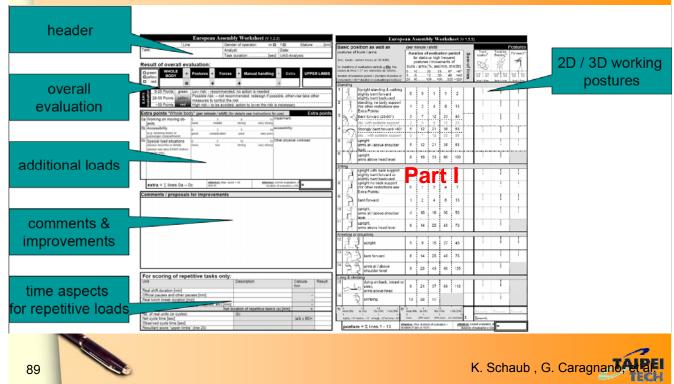
Source: Introduction to EAWS (Ergonomic Assessment Worksheet)

Workshop

Dipl.-Ing. Torsten Wagner - IAD. 2012

EAWS Worksheets





EAWS Worksheets



forces

extract from force atlas

The process of the pr

Upper Emb load in specific lasts

O printed of six action [10]

I printed of six action [10]

I

repetitive loads

manual materials handling



EAWS lamp system



Whole Body (p1~3)



Upper Limbs (p4)















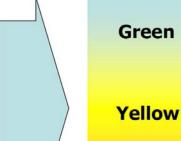
- Unfavorable posture
- Heavy loads
- Moving heavy loads
- Repetitive tasks
- High frequency (Sorting of goods)
- Strength (Insertion of finger)
- High precision (Using clips)



Risk Levels

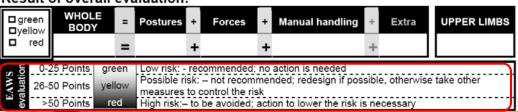


- 1a. Sum up "working postures", "action forces" and "manual materials handling" for total score "WHOLE BODY"
- 1b. Calculate score for "UPPER LIMBS"
- Assign traffic light color dependent from scores (worst case of "whole body" or "upper limbs")



Red

Result of overall evaluation:

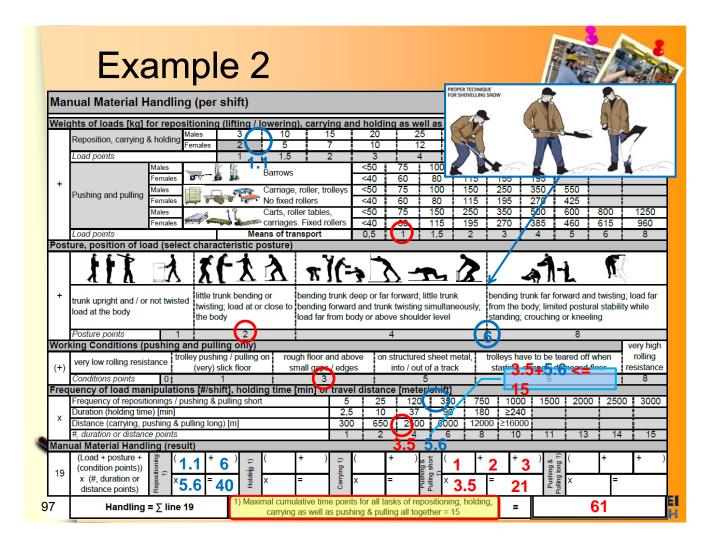


Assessment Procedure Consider: Force Part 1 >30 / 40 N posture **Posture** duration Loads mainly from posture Consider: Part 2 LHC or posture PP task? **Force** force duration Loads on fingers /hands and on to joints Consider: Part 3 posture **MMH** force work condition Loads on spine! duration

Example 1: 油漆作業 A painter's tasks in a work shift: Paint ceiling (2.5 hrs) - standing(6), 1.4 hrs (84 min) - standing(2), 1.1 hrs (66 min) Paint wall (3.5 hrs) - standing(2), 1 hr (60 min) - standing(3) bend forward, 0.8 hr (48 min) - standing(5) elbow at shoulder level, 0.7 hr (42 min) - Crouching(12), 0.5 hr (30 min) - Crouching(13) bend forward, 0.5 hr Break (sitting, 2 hrs)

Ва	sic Po	sitions / Postures and	ents	of t	runk	and	d arr	ns (oer s	shift)						ostures	
ford	l. loads es onto I whole b	Evaluation of static postures and/or high frequent movements of trunk/arms/legs									Sı	Trur Rotatio	nk	Lateral Bending 1)	Far Reach			
Sta	tic postu	stures: ≥ 4sec			Duration [sec/min] = \frac{duration of posture(s) \times 60}{cycle time}								Sum of lines					
Tru	nk bend eeling/cr	ncy movements: ings (> 60°) ≥ 2/min ouching ≥ 2/min (> 60°) ≥ 10/min	[%] [sec/min] [min/8h]		7,5 4,5 36	6	15 9 72	20 12 96	27 16	33 20	50 30	40	50	lines	int 0-5 Intens	ity x	int dur 0-5 0-3 Intensity x Duration	int dur 0-5 0-2 Intensity x Duration
Sta	nding (a	and walking)																
1	3 180	Standing & walking in alteration standing with support	on,	0	0	0	0	0,5	1	1	1	1,5	2					
2	Ĵ	Standing, no body support (for or restrict. see Extra Points) Bent forward (20-60°) with suitable support		0,7	1	1,5	2	3	4	6	8	11	13	4				
3	<u> </u>			2 1,3	3 2	5	7 5	9,5 6,5	12	18	23 15	32 20	40 25	5				
4	Strongly bent forward (>60°) with suitable support			3,3	5	8,5	12 7	17 9,5	21 12	30 18	38 23	51 31	63 38	0				
5	4			3,3	5	,5	12	17	21	30	38	51	63	7				
6	Ŋ	Upright with hands above hea	ad level	5,3	8	14	19	26	33	47	60	80	100	22.5				
Sitt	ing												_					
7	Å	Upright with back support slightly bent forward or backw	/ard	0	0	0)	0	0	0,5	1	1,5	2	0				
Kn	eling o	r crouching																
12	ŽŽ	Upright		3,3	 5	7	9	12	15	21	27	36	45	4.1				
13	32.2 2.3	Bent forward		4	В	10	14	20	25	35	45	60	75	5				
14	22	Elbow at / above shoulder lev	el	6	9	16	23	33	43	62	80	108	135					
		Postures = ∑ lines 1 -	16			47	7	Т	+					=				





Example 3: 布匹推送作業



- A式推車裝載>300kg
- 染布作業一天染8批次,每一批次可染 洗4車A,A車布料經過染洗後可產出8 台B車
- A車推送距離約15公尺(總距離480 m), B車約25公尺(總距離1550 m)。
- 推送B式推車時所需施力大小約為A式 推車之2.5~3倍

• B式推車裝載 約800kg







ເ Example 3 KIM - PP檢核表

K	IM 風險等級評估	評級點數			
IX	1101 風險守放許但	Α	В		
負載重量	定向輪軌道車300 / 800 kg	3	5		
定位準確	低、慢 (<0.8 m/s)	1	1		
度與速度	受限制(地面濕滑)	I	'		
姿勢	軀幹前彎或彎腰	3	3		
工作狀況	地面濕滑	1	1		
時間評級	總距離480 / 1550 m	2	4		

A風險值: (3+1+3+1)x2 = 16 ←

B風險值: (5+1+3+1)x4 = 40 ✓

B式推車約 800kg,推送 距離約25公 尺

染布作業一 天染8批次, 每一批次可 染洗4車A, A車布料經過 染洗後可產 出8台B車



Evample 3

_		ing (per	shift)								Load
П	hts of loads [kg] for rep	ositioning	g (lifting / l	owering),	carrying a	nd holdin	g as well a	s pushing ar	nd pulling		
	Reposition, carrying & holding	Males	3	10	15	20	25	30	35	40	>40
L	. ,	Females	2	5	7	10	12	15	20	25	>25
ļ	Load points		1	1,5	2	3	4	5,5	7	8,5	25
١	Males Female	s 5		Barrows		<50 <40		00 150 1	200 <u>250</u>		-
+	Males	rf=d -		Carriage, ro	oller, trolleys			00 150	250 350	550	_
- 1	Pushing and pulling Female	Females Females		No fixed roll		<40	60 8	0 115	195 270	425	
- 1	Males	A The	19	Carts, roller		<50		50 250	350 500	600 800	
ı	Female	S		carriages. F		<40			270 385	460 61	
	Load points			ans of trans	port	0,5	1 1	,5 2 2	53 4	<u> 5 66</u>	8
sti	ure, position of load (se	lect chara	cteristic p	osture)		1					
	trunk upright and / or not twi		unk bending or load at o				forward; little			forward and twis	
	load at the body		ıg; load at o	close to be	ending forwa ad far from b	rd and trunk ody or abov	twisting sim	nultaneously; fi		nited postural sta ng or kneeling	
	load at the body Posture points	twisting the bo	ng; load at or ody 2	r close to be	ending forwa ad far from b	rd and trunk ody or abov	twisting sim	nultaneously; fi	rom the body; lim	nited postural sta	ability while
ork	load at the body Posture points king Conditions (pushin	twisting the book trolley pushing steed twisting the book trolley pushing trolley pushing steed twisting	ng; load at or ody 2 ling only) ing / pulling	r close to be	ending forwa ad far from b floor and ab	rd and trunk ody or abov	twisting sim ye shoulder le	eet metal, tr	rom the body; lim standing; crouchi	nited postural sta ng or kneeling 8 e teared off when	very hig
ork +)	load at the body Posture points ting Conditions (pushin very low rolling resistance	twisting the boot trolley pushing (very)	ng; load at or ody 2 ling only) ing / pulling	r close to be	ending forwa ad far from b floor and ab Il gaps / edg	rd and trunk ody or abov	t twisting simulation in the structured shinto / out of a	nultaneously; frevel s eet metal, tra	rom the body; lin standing; crouchi olleys have to be starting, strongly	nited postural sta ng or kneeling 8	very hig rolling resistan
ork +)	load at the body Posture points (ing Conditions (pushin very low rolling resistance Conditions points 0	twisting the boot twisting the boot the	g; load at or ody 2 ling only) ing / pulling	on rough	ending forwa ad far from b floor and ab Il gaps / edg 3	rd and trunk lody or abov love on s es	t twisting sim ve shoulder le tructured sh into / out of a	eet metal, tra	rom the body; lim standing; crouchi	nited postural sta ng or kneeling 8 e teared off when	very hig
ork +)	load at the body Posture points king Conditions (pushin very low rolling resistance Conditions points 0 uency of load manipula	twistin the bo	g; load at or ody 2 ling only) ing / pulling click fleor 1	on rough sma	ending forwa ad far from b floor and ab Il gaps / edg 3	ove on see	twisting simple shoulder leads to the structured shoulder leads to the structured should be should b	eet metal, tra	rom the body; lin standing; crouchi olleys have to be starting, strongly	nited postural sta ng or kneeling 8 e teared off when	very hig rolling resistan
ork +)	load at the body Posture points (ing Conditions (pushin very low rolling resistance Conditions points 0	twistin the both trolley pushin (very); tions [#/sh	g; load at or ody 2 ling only) ing / pulling click fleor 1	on rough sma	ending forwa ad far from b floor and ab Il gaps / edg 3 in] or trav	ove on see of distance 25	t twisting sim ve shoulder le tructured sh into / out of a	eet metal, track	rom the body; limitanding; crouching crouching crouching of the starting at th	nited postural sta ng or kneeling 8 e teared off when	very hig rolling resistan
ork +) equ	load at the body Posture points (Ing Conditions (pushin very low rolling resistance Conditions points uency of load manipula Frequency of repositionings Duration (holding time) [min Distance (carrying, pushing	twistin the bo	ing load at ordy 2 ing only) ing / pulling plack floor ind, molding pulling shor	on rough sma	ending forwa ad far from b floor and ab Il gaps / edg 3 in] or trav	oove on see of the control of the co	stwisting simple shoulder leads to structured shinto / out of a second shiple s	eet metal, tra a track 1.5+ 1.5+ 90 180	rom the body; limitanding; crouching crouching of the body and the body and the body are the body and the body are the body and the body are the body; limit and the body; limit are the bod	nited postural sta ng or kneeling 8 e teared off when	very hig rolling resistan
ork +) equ	Posture points Ing Conditions (pushin very low rolling resistance Conditions points 0 uency of load manipular Frequency of repositionings Duration (holding time) [min Distance (carrying, pushing #, duration or distance point	twistin the bot the bo	ing load at ordy 2 ing only) ing / pulling plack floor ind, molding pulling shor	on rough sma	floor and abiling for travial states of the	ove on ses 25 10 0 1550	structured shinto / out of structured shinton / out of structured	eet metal, tra a track 1.5+ 1.5+ 90 180	rom the body; limitanding; crouching crouching of the body and the body and the body and the body are to be body and the body; limitanding are to be body and the body; limitanding are to be body; limitanding; crouching are to be body	8 e teared off when demaged floor	very hig rolling resistan
ork ·) equ	load at the body Posture points (Ing Conditions (pushin very low rolling resistance Conditions points uency of load manipula Frequency of repositionings Duration (holding time) [min Distance (carrying, pushing #, duration or distance point ual Material Handling (re	twistin the bot trolley push (very); tions [#/sh / pushing & [#/sh] & pulling lons sesult)	ing load at ordy 2 ing only) ing / pulling plack floor ind, molding pulling shor	on rough sma	floor and abiling for travial states of the	ove on ses 25 10 0 1550	structured shinto / out of structured shinton / out of structured	eet metal, tra track 1.5+ inift) 350 750 90 180 6000 12000	olleys have to be 1000 150 ≥240 0 ≥16000	8 e teared off when demaged floor	very high rolling resistan 8
ork +) equ	load at the body Posture points (Ing Conditions (pushin very low rolling resistance Conditions points uency of load manipula Frequency of repositionings Duration (holding time) [min Distance (carrying, pushing #, duration or distance point ual Material Handling (re	twistin the bot the bo	ag; load at or ody 2 ing only) ing / pulling ing / pulling ing / polling	on rough sma	floor and abiling for trav injor trav 5 2, 300 1	ove on ses 25 10 0 1550	structured shinto / out of structured shinton / out of structured	eet metal, tra track 1.5+ inift) 350 750 90 180 6000 12000	rom the body; limitanding; crouchii colleys have to be planting, strongly 3 <= 15 1000 150 ≥240 10 11	8 e teared off when demaged floor	very high rolling resistan 8 2500 300
ork +) equ	load at the body Posture points (ing Conditions (pushin very low rolling resistance Conditions points 0 uency of load manipular Frequency of repositionings Duration (holding time) [min Distance (carrying, pushing #, duration or distance point ual Material Handling (re (Load + posture + (condition points))	twistin the bot trolley push (very); tions [#/sh / pushing & [#/sh] & pulling lons sesult)	ing load at ordy 2 ing only) ing / pulling plack floor 1 pulling shor	on rough sma	floor and abiling for travial states of the	ove on ses 25 10 0 1550	structured shinto / out of a structured shinton / out of a structured shin	eet metal, tra track 1.5+ inift) 350 750 90 180 6000 12000	rom the body; limitanding; crouchii colleys have to be planting, strongly 3 <= 15 1000 150 ≥240 10 11	8 e teared off when demaged floor	very high rolling resistan 8

Example 4: Coil Packing

Push / Pull



- 推動鋼捲,將鋼捲 安置於打包機,並 將打包完畢之鋼捲 推至定位以便進行 固定及綑綁。
- 彎腰行走,推動距離平均約7m/次,每日約500~700m。8% (0.7 hr)
- 鋼捲重量300~
 1000 kg,平均約
 570 kg。

10

Posture (<40N)





- 從事吊掛、理貨、 取物、設備控制等 作業。47% (4 hr)
- 直立站姿,低施力
- 用餐休息,坐姿, 12% (1 hr)





- 彎腰站姿/蹲跪姿, 進行鋼捲固定及綑 綁。33% (2.8hr/168min)
- 彎腰站姿:96 min
- 蹲跪姿:72 min



Example 4

Force (>40N)



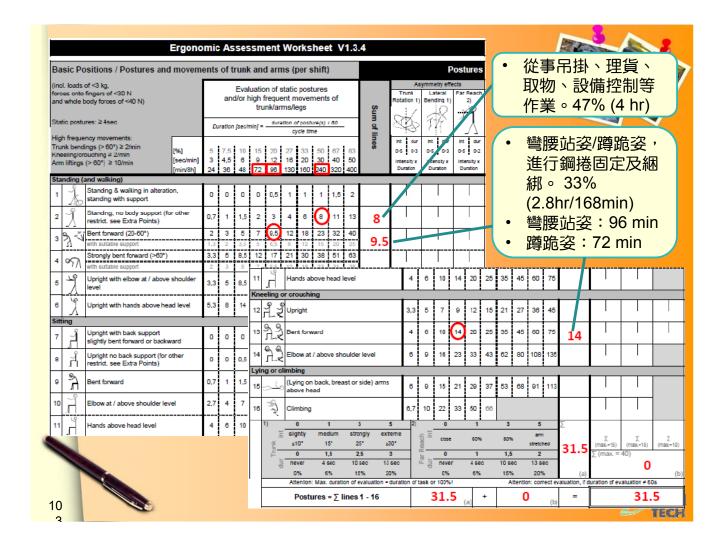


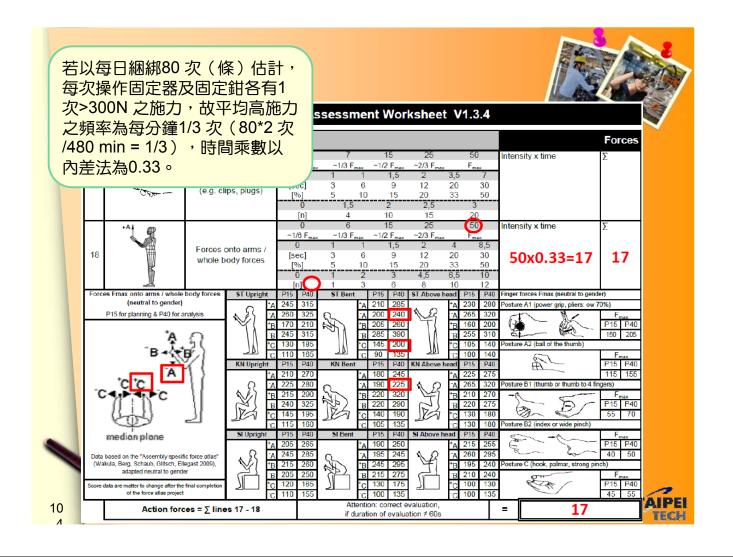


- 彎腰站姿,使用工具及鉗子 進行鋼捲固定及綑綁作業。
- 高施力,彎腰站姿。
- 估計每日操作>60 次,每次 操作綑綁工具單手及雙手需 分別反覆拉/壓10 次,手部所 需最大下壓/拉力達300N。











Example 4: Coil Packaging



Result of ov	erall evaluation:		carculate the lotal score of the whole body sections and compare it to the upper limbs score, the overall result is determined by the higher value but interpretation should also take into account the second value.											
Green	Whole Body	=	Postures	+	Forces	+	Loads	+	Extra	Upper Limbs				
☐ Yellow☐ Red	66.5	=	31.5	+	17	+	18	+	0					
		_												

	ion	0-25 Points	Green	Low risk: recommended; no action is needed
ı	-AW	>25-50 Points	Yellow	Possible risk: not recommended; redesign if possible, otherwise take other measures to control the risk
ľ	eva	>50 Points	Red	High risk: to be avoided; action to lower the risk is necessary



